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## WHAT IS CLAIMED; IS

- 1. Method for the correction of video signals which are transmitted pixel by pixel as digital pixel values alternately via at least two channels having different transfer characteristics, characterized in that, from the pixel values transmitted via a first channel, estimated values for the pixels of a second channel are formed by means of interpolation, and in that
- correction values for the pixel values of the second channel are derived from differences between the estimated values and the pixel values of the second channel.
- 2. Method according to Claim 1, characterized in that the correction values are only formed from those differences which are less than a predetermined value (K1).
- 3. Method according to Claim 1, characterized in that, further estimated values are formed from pixel values which are transmitted by interpolation by means of the second channel, in that further differences are formed from the further estimated values and the pixel values of the first channel, in that an average value
- values of the first channel, in that an average value is in each case formed from the differences and the further differences, and in that the correction values are derived from the average values.
- 4. Method according to Claim 2, characterized in that, further estimated values are formed from pixel values which are transmitted by interpolation by means of the second channel, in that further differences are formed from the further estimated values and the pixel
- values of the first channel, in that an average value is in each case formed from the differences and the further differences, and in that the correction values are derived from the average values.

- 5. Method according to Claim 3, characterized in that the differences and the further differences are in each case subtracted from one another, and in that the respective average value of the differences is only used for correction if the value produced by subtraction of the difference and the further difference is less than a further predetermined value (K2).
- 10 6. Method according to Claim 4, characterized in that the differences and the further differences are in each case subtracted from one another, and in that the respective average value of the differences is only used for correction if the value produced by subtraction of the difference and the further difference is less than a further predetermined value (K2).
- 7. Method according to Claim 1, characterized in that
  20 the differences and the further differences, for the
  purpose of forming the correction values, are averaged
  separately according to the magnitude of the pixel
  values, in that the correction values are written to a
  memory, and in that the correction values are read from
  25 the memory depending on the respective magnitude of the
  pixel values and are added to the pixel values of the
  first and/or the second channel.
- 8. Method according to Claim 3, characterized in that
  30 the averaging is in each case effected separately
  according to magnitude ranges of the pixel values, and
  in that correction values are obtained for the
  individual pixel values by interpolation and low-pass
  filtering of the mean values within the various
  35 magnitude ranges.
  - 9. Method according to Claim 7, characterized in that the averaging is in each case effected separately according to magnitude ranges of the pixel values, and

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in that correction values are obtained for the individual pixel values by interpolation and low-pass filtering of the mean values within the various magnitude ranges.

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10. Method according to Claim 1, characterized in that the only pixel values which are evaluated are those which change at a rate (f) which is below a cut-off frequency (F).

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11. Method according to Claim 1, characterized in that the only pixel values which are evaluated are those which change at a rate which is below the Nyquist frequency (N/4).

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12. Method according to Claim 10, characterized in that the cut-off frequency depends on the predetermined value (K1) or on the further predetermined value (K2).